Fourier Analysis from the context of the course MTH 496: Capstone in Fourier Analysis

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### Chapter 1

## **Discrete Fourier Analysis**

#### 1.1 Complex Numbers

**Definition 1.1.1.** The set of complex numbers  $\mathbb{C}$  is defined where  $i^2 = -1$  by

$$\mathbb{C} = \{a + bi : a, b \in \mathbb{R}\}\$$

**Definition 1.1.2.** The complex conjugate of a complex number  $a + bi = z \in \mathbb{C}$  denoted  $\overline{z}$  is defined as  $\overline{z} = a - bi$ .

**Definition 1.1.3.** The norm of a complex number  $z \in \mathbb{C}$  denoted |z| is defined as  $|z| = \sqrt{z\overline{z}}$ .

**Theorem 1.1.1. Taylor's Theorem** states that any  $C^{\infty}$  continuous function  $f : \mathbb{C} \to \mathbb{C}$  can be represented as a Taylor series centered at any point  $a \in \mathbb{C}$ .

$$f(z) = \sum_{n=0}^{\infty} \frac{f^{(n)}(a)}{n!} (z-a)^r$$

**Theorem 1.1.2. Euler's Formula** states that for any real number  $\varphi \in \mathbb{R}$ ,

$$e^{i\phi} = \cos\phi + i\sin\phi$$

**Proposition 1.1.1.** Any complex number  $z \in \mathbb{C}$  can be represented in the form  $z = re^{i\phi}$ .

**Definition 1.1.4.** A field R is a set with two laws of composition denoted + and  $\times$  that satisfy the following axioms:

- Identity  $\exists$  elements denoted  $0, 1 \in R$  such that  $1 \times a = a$  and  $0 + a = a, \forall a \in R$ .
- Additive Inverse For all  $a \in R$ , there exists an element  $-a \in R$  such that -a + a = 0.
- Multiplicative Inverse For all nonzero  $a \in F$ , there exists an element  $a^{-1} \in R$  such that  $a \times a^{-1} = 1$ .
- Associativity For all  $a, b, c \in R$ ,  $a \times (b \times c) = (a \times b) \times c$  and a + (b + c) = (a + b) + c.
- Commutativity For all  $a, b \in R$ ,  $a \times b = b \times a$  and a + b = b + a.
- **Distributivity** For all  $a, b, c \in R$ ,  $a \times (b + c) = (a \times b) + (a \times c)$ .

**Proposition 1.1.2.** The complex numbers  $\mathbb{C}$  is a field with multiplicative inverses  $z^{-1} = \frac{\overline{z}}{|z|^2}$  for any  $z \in \mathbb{C}$ . **Proposition 1.1.3.**  $\mathbb{R}$  is a subfield of  $\mathbb{C}$ .

#### **1.2** Complex Vectors

**Definition 1.2.1.** The index set of size  $N \in \mathbb{N}$  denoted [N] is the set  $[N] = \{0, \dots, N-1\}$ .

**Definition 1.2.2.** the **Nth complex vector space** is the set  $\mathbb{C}^N$  of vectors  $\mathbf{v} \in \mathbb{C}^N$  with N complex components  $v_j \in \mathbb{C}$ . **Definition 1.2.3.** The **dot product** or **Hadamard product** of two vectors  $\mathbf{u}, \mathbf{v} \in \mathbb{C}^N$  denoted  $\mathbf{u} \cdot \mathbf{v}$  is defined by

$$(\mathbf{u} \cdot \mathbf{v})_j = u_j \cdot v_j$$

#### **1.3** Discrete Fourier Transform

**Definition 1.3.1.** The discrete Fourier transform (DFT) is a linear transformation  $F : \mathbb{C}^n \to \mathbb{C}^n$  defined with the  $n \times n$  matrix

$$F_{\omega,j} = \frac{1}{\sqrt{n}} e^{-2\pi i \omega j/n}$$

The DFT of a vector  $\mathbf{v} \in \mathbb{C}^n$  is  $\hat{\mathbf{v}} = F\mathbf{v} \in \mathbb{C}^n$ .

**Definition 1.3.2.** A linear transformation is unity iff  $U^{\dagger}U = I$ .

**Proposition 1.3.1.** The DFT matrix F is unitary.

**Definition 1.3.3.** The inverse discrete Fourier transform (IDFT) is the inverse  $F^{-1} = F^{\dagger}$ .

**Theorem 1.3.1.** The **fast Fourier transform** is an algorithm for quickly computing the Fourier transform of a vector  $\mathbf{u} \in \mathbb{C}^N$ . Let  $N = p_1 p_2 \dots p_m$  be the unique prime factorization of N.

$$\widehat{u}_{\omega} = \frac{1}{\sqrt{N}} \sum_{k=0}^{p_1-1} \widehat{u^{(k,p_1)}}_{\omega \mod \frac{N}{p_1}} e^{-2\pi i \omega k/N}$$

**Result 1.3.1.** The fomplexity of the fast Fourier transform for  $N = 2^m$  is  $\mathcal{O}(N \log N)$ 

#### **1.4** Convolutions

**Definition 1.4.1.** The circular convolution of two vectors  $\mathbf{u}, \mathbf{v} \in \mathbb{C}^N$  denoted  $\mathbf{u} * \mathbf{v}$  is defined as

$$(\mathbf{u} * \mathbf{v})_k = \sum_{j=0}^{N-1} u_j v_{(k-j) \mod N}$$

Corollary 1.4.0.1. The circular convolution is commutative.

**Definition 1.4.2.** A matrix is **circulant** iff all row vectors are composed of the same elements and each row vector is rotated one element to the right relative to the preceding row vector.

**Proposition 1.4.1.** The circular convolution by a vector  $\mathbf{v} \in \mathbb{C}^N$  can be represented as a circulant matrix:

$$\operatorname{circ}(\mathbf{v})_{kj} = v_{(j-k) \mod N}$$

**Theorem 1.4.1.** Let  $\mathbf{u}, \mathbf{v} \in \mathbb{C}^N$  then  $(\widehat{\mathbf{u} * \mathbf{v}})_{\omega} = (F(\mathbf{u} * \mathbf{v}))_{\omega} = \sqrt{N} \widehat{u}_{\omega} \cdot \widehat{v}_{\omega}, \forall \omega \in [N].$ 

Corollary 1.4.1.1. For any  $\mathbf{u}, \mathbf{v} \in \mathbb{C}^N$ ,  $\mathbf{u} * \mathbf{v} = \sqrt{N} F^{\dagger}(F\mathbf{u} \cdot F\mathbf{v}) = \sqrt{N} (\widehat{\widehat{\mathbf{u}} \cdot \widehat{\mathbf{v}}}).$ 

Corollary 1.4.1.2. For any  $\mathbf{u}, \mathbf{v} \in \mathbb{C}^N$ ,

$$\widehat{u}_{\omega} = \left(F\mathbf{u}\right)_{\omega} = \frac{\left(F\left(\mathbf{u} * \mathbf{v}\right)\right)_{\omega}}{(F\mathbf{b})_{\omega}\sqrt{N}} = \frac{\left(\widehat{\mathbf{u} * \mathbf{v}}\right)_{\omega}}{\widehat{b}_{\omega}\sqrt{N}}$$

**Theorem 1.4.2.** The eigenvectors of  $circ(\mathbf{v})$  for any  $\mathbf{v} \in \mathbb{C}^N$  are the columns of  $F^{\dagger}$ .

**Proposition 1.4.2.** For two polynomials  $g(x) = \sum_{j=0}^{N-1} g_j x^j$  and  $r(x) = \sum_{j=0}^{N-1} r_j x^j$ . The product of the two polynomials has at most degree 2N - 2 and can be computed by convolving the two polynomial vectors padded with N - 1 zeros.

$$g(x)r(x) = \mathbf{g} * \mathbf{r} = \begin{pmatrix} g_0 \\ \vdots \\ g_{N-1} \\ 0 \\ \vdots \\ 0 \end{pmatrix} * \begin{pmatrix} r_0 \\ \vdots \\ r_{N-1} \\ 0 \\ \vdots \\ 0 \end{pmatrix}$$

#### **1.5** Trigonometric Polynomials

**Definition 1.5.1.** A trigonometric polynomial of degree N is a function  $p : \mathbb{R} \to \mathbb{C}$  defined by

$$p(x) = \sum_{\omega = -N}^{N} p_{\omega} e^{-\omega x}$$

**Corollary 1.5.0.1.** A trigonometric polynomial is  $2\pi$  periodic.

**Definition 1.5.2.** The inner product of trigonometric polynomials  $p, q \in \mathbb{C}^{2N+1}$  is defined

$$\langle p,q \rangle = \frac{1}{2\pi} \int_{-\pi}^{\pi} p(x) \overline{q(x)} dx = \sum_{\omega=-N}^{N} p_{\omega} \overline{q}_{\omega}$$

**Definition 1.5.3.** The norm of a trigonometric polynomial  $p \in \mathbb{C}^{2N+1}$  is defined by

$$||p||^{2} = \langle p, p \rangle = \frac{1}{2\pi} \int_{-\pi}^{\pi} |p(x)|^{2} dx = \sum_{\omega = -N}^{N} |p_{\omega}|^{2}$$

**Definition 1.5.4.** The Fourier transform of a trigonometric polynomial  $p \in \mathbb{C}^{2N+1}$  is defined as

$$F[p](\omega) = \hat{p}_{\omega} = \langle p, e^{i\omega x} \rangle = p_{\omega} = \frac{1}{2\pi} \int_{-\pi}^{\pi} p(x) e^{-i\omega x} dx$$

**Definition 1.5.5.** The **Inverse Fourier transform of a trigonometric polynomial**  $\hat{p}_{\omega} \in \mathbb{C}^{2N+1}$  is defined as

$$F^{-1}[\widehat{p}](x) = \sum_{\omega = -N}^{N} \widehat{p}_{\omega} e^{i\omega x}$$

**Definition 1.5.6.** The convolution of two trigonometric polynomials  $p, q \in \mathbb{C}^{2N+1}$  denoted p \* q is defined

$$(p*q)(y) = \frac{1}{2\pi} \int_{-\pi}^{\pi} p(x)q(y-x)dx$$

**Theorem 1.5.1.**  $F[p * q](\omega) = F[p](\omega) \cdot F[q](\omega) = \widehat{p}_{\omega} \cdot \widehat{q}_{\omega} \quad \forall \omega \{-N, \dots, N\}$ 

**Corollary 1.5.1.1.**  $\deg(p * q) \le \min\{\deg(p), \deg(q)\}$ 

**Theorem 1.5.2.** Let  $p \in \mathbb{C}^{2N+1}$  be a trigonometric polynomial with Fourier transform  $\hat{p}_{\omega}$ . The discrete Fourier transform  $\hat{v}$  of the vector v defined by  $v_j = p\left(\frac{2\pi j}{2N+1}\right)$  is the reordered elements of  $\hat{p}_{\omega}$ .

$$\begin{pmatrix} \hat{p}_{0} \\ \vdots \\ \hat{p}_{N} \\ \hat{p}_{-N} \\ \hat{p}_{-N+1} \\ \vdots \\ \hat{p}_{-1} \end{pmatrix} = \frac{\hat{v}}{\sqrt{2N+1}}$$

**Corollary 1.5.2.1.** For a trigonometric polynomial  $p \in \mathbb{C}^{2N+1}$ ,  $\hat{p}_{\omega} = \frac{2\pi}{2N+1} \sum_{j=0}^{2N} p\left(\frac{2\pi j}{2N+1}\right) e^{\frac{-2\pi i j \omega}{2N+1}}$ 

**Theorem 1.5.3.** For an infinite trigonometric polynomial  $p \in \mathbb{C}^{\infty}$ , defined by  $p(x) = \sum_{\omega \in \mathbb{Z}} c_{\omega} e^{i\omega x}$  and a finite sampling  $u \in \mathbb{C}^N$  defined by  $c_j = p\left(\frac{2\pi j}{N}\right)$ , the Fourier transform of u is

$$\widehat{u}_{\omega} = \sqrt{N} \sum_{j=\omega \mod N} \widehat{p}_j$$

### 1.6 Heat Equation

Definition 1.6.1. The heat equation is a differential equation of the form

$$\frac{\partial u}{\partial t} = k \frac{\partial^2}{\partial x^2} u - f$$

where u(x,t), u(x,0), and f(x) are degree  $\leq N$  trigonometric polynomials.

$$u(x,t) = \sum_{\omega=-N}^{N} \widehat{u}_{\omega}(t) e^{i\omega x}$$

Proposition 1.6.1. The derivative of the Fourier transform can be written as

$$\frac{\partial}{\partial t}\widehat{u}_{\omega}(t) = -k\omega^{2}\widehat{u}_{\omega}(t) - \widehat{f}_{\omega}$$

**Proposition 1.6.2.** For  $\omega \neq 0$  the Fourier transform of the solution to the heat equation is

$$\widehat{u}_{\omega}(t) = e^{-k\omega^2 t} \left( \widehat{u}_{\omega}(0) + \frac{\widehat{f}_{\omega}}{k\omega^2} \right) - \frac{\widehat{f}_{\omega}}{k\omega^2}$$

Theorem 1.6.1. The solution to the heat equation can be written in terms of discrete Fourier transforms

$$u(x,t) = \sum_{\omega=-N}^{N} \left( e^{-k\omega^2 t} \left( \overline{u}_{\omega}(0) + \frac{\widehat{f}_{\omega}}{k\omega^2} \right) - \frac{\widehat{f}_{\omega}}{k\omega^2} \right) e^{i\omega x} + \widehat{g}_o$$

### Chapter 2

## **Fourier Series**

#### 2.1 Riemann Integrability

**Definition 2.1.1.** A partition  $P_N$  of [a, b] is a set of N ordered points  $P_N \subset [a, b]$  denoted  $P_N = \{x_0, x_1, \ldots, x_{N-1}\}$  such that

 $a = x_0 < x_1 < \dots < x_{N-1} = b$ 

**Definition 2.1.2.** The mesh size of a partition  $P_N$  is  $\max_{i \in [0, N-2] \cap \mathbb{Z}} |x_{i+1} - x_i|$ 

**Definition 2.1.3.** The upper and lower sums denoted  $L(f, P_N)$  and  $U(f, P_N)$  of a function f with partition  $P_N$  are defined

$$U(f, P_N) = \sum_{j=0}^{N-2} \sup_{t \in [x_j, x_{j+1}]} (x_{j+1} - x_j)$$
$$L(f, P_N) = \sum_{j=0}^{N-2} \inf_{t \in [x_j, x_{j+1}]} (x_{j+1} - x_j)$$

**Definition 2.1.4.** A function f is a **Riemann integrable function** iff  $\forall \varepsilon > 0$ , there exists  $P_N$  with  $\varepsilon(P_N) < \varepsilon$  such that

$$|L(f, P_N) - U(f, P_N)| < \varepsilon$$

**Definition 2.1.5.** A complex function  $f : [a, b] \to \mathbb{C}$  is a complex Riemann integrable function iff both  $\operatorname{Re}(f)$  and  $\operatorname{Im}(f)$  are Riemann integrable.

Corollary 2.1.0.1. A continuous function is Riemann integrable.

**Definition 2.1.6.** A function  $f : [a, b] \to \mathbb{C}$  is **piecewise continuous** denoted  $f \in P([a, b])$  iff there exists a finite set of points  $\{x_0, x_1, \ldots, x_{N-1}\} = D \subset [a, b]$  such that f is continuous on the following intervals

$$(a, x_0), (x_0, x_1), \dots, (x_{N-2}, x_{N-1}), (x_{N-1}, b)$$

**Theorem 2.1.1.** If a function f is piecewise continuous and bounded then it is Riemann integrable.

**Definition 2.1.7.** A function  $f : [a,b] \to \mathbb{C}$  is a **piecewise smooth** denoted  $f \in PS([a,b])$  iff f, f' both exist and are piecewise continuous.

**Definition 2.1.8.** The inner product of functions  $f, g : [a, b] \to \mathbb{C}$  is defined

$$\langle f,g \rangle = \frac{1}{2\pi} \int_{-\pi}^{\pi} f(x) \overline{g(x)} dx$$

#### 2.2 Bessel's Inequality

**Definition 2.2.1.** The Fourier coefficients denoted  $c_n, a_n, b_n$  of a function  $f : [a, b] \to \mathbb{C}$  are

$$c_n = \frac{1}{b-a} \int_a^b f(\theta) e^{\frac{-2\pi i n\theta}{b-a}} d\theta$$
$$a_n = \frac{2}{b-a} \int_a^b f(\theta) \cos\left(\frac{2\pi n\theta}{b-a}\right) d\theta$$
$$b_n = \frac{2}{b-a} \int_a^b f(\theta) \sin\left(\frac{2\pi n\theta}{b-a}\right) d\theta$$

**Corollary 2.2.0.1.** The Fourier coefficients for a  $2\pi$ -periodic function  $f: [-\pi, \pi] \to \mathbb{C}$  are

$$c_n = \frac{1}{2\pi} \int_{-\pi}^{\pi} f(\theta) e^{-in\theta} d\theta$$
$$a_n = \frac{1}{\pi} \int_{-\pi}^{\pi} f(\theta) \cos(n\theta) d\theta$$
$$b_n = \frac{1}{\pi} \int_{-\pi}^{\pi} f(\theta) \sin(n\theta) d\theta$$

**Theorem 2.2.1. Bessel's Inequality** states that if  $f : [a, b] \to \mathbb{C}$  is Riemann integrable then

$$\sum_{n = -\infty}^{\infty} |c_n|^2 \le \frac{1}{b - a} \int_{-a}^{b} |f(\theta)|^2$$

**Corollary 2.2.1.1.** If  $f: [-\pi, \pi] \to \mathbb{C}$  is  $2\pi$ -periodic and Riemann integrable then

$$\sum_{n=-\infty}^{\infty} |c_n|^2 \le \frac{1}{2\pi} \int_{-\pi}^{\pi} |f(\theta)|^2$$

Corollary 2.2.1.2. The Fourier series converges absolutely.

**Definition 2.2.2.** The Nth parital Fourier sum of a function  $f : [a, b] \to \mathbb{C}$  denoted  $S_N^f(\theta)$  defined

$$S_N^f(\theta) = \sum_{n=-N}^N c_n e^{in\theta}$$

**Theorem 2.2.2.** If  $f : [a, b] \to \mathbb{C}$  is a piecewise smooth function that is  $f \in PS([a, b])$  with discontinuities  $\{x_0, x_1, \dots\}$  then

$$\lim_{N \to \infty} S_N^f(\theta) = f(\theta), \quad \forall \theta \in [a, b] - \{x_0, x_1, \dots\}$$

#### 2.3 The Dirchlet Kernel

**Definition 2.3.1.** The **Dirchlet Kernel** denoted  $D_N(y)$  is defined

$$D_N(y) = \frac{1}{2\pi} \sum_{k=-N}^N e^{iky}$$

**Corollary 2.3.0.1.** For any function  $f : [a, b] \to \mathbb{C}, S_N^f(\theta) = (D_N * f)(\theta).$ 

**Proposition 2.3.1.** The Dirchlet kernel can be written in terms of sin,  $D_N(y) = \frac{\sin((N+1/2)y)}{\sin(y/2)}$ 

**Proposition 2.3.2.** The following properties of the Dirchlet kernel  $D_N(y)$  hold for all  $N \in \mathbb{N}$ .

- $D_N(0) = 2N + 1$
- The Dirchlet kernel is  $2\pi$ -periodic
- $|D_N(y)| \le \frac{1}{|\sin(y/2)|}$
- $D_N\left(\frac{2\pi}{2N+1}k\right) = 0$  for  $k \in \{-N, \dots, -1, 1, \dots, N\}$

• 
$$\frac{1}{2\pi} \int_{-\pi}^{\pi} D_N(y) = 1$$

•  $\frac{1}{2\pi} \int_{-\pi}^{0} D_N(y) = \frac{1}{2\pi} \int_{0}^{\pi} D_N(y) = \frac{1}{2}$ 

**Theorem 2.3.1.** The  $S_N^f$  is piecewise continuous and bounded.

**Theorem 2.3.2.** If  $f : [a, b] \to \mathbb{C}$  is a piecewise smooth function that is  $f \in PS([a, b])$  with discontinuities  $\{x_0, x_1, \dots\}$  then

$$\lim_{N \to \infty} S_N^f(\theta) = \frac{f(\theta^-) + f(\theta^+)}{2}, \quad \forall \theta \in [a, b]$$

**Proposition 2.3.3.** The Cardinality of  $PS([-\pi, \pi])$  is  $|\mathbb{R}|$ .

#### 2.4 Smoothness

**Definition 2.4.1.** A function f is  $C^k$  smooth iff  $f^{(k)}$  exists and is Riemann integrable.

**Corollary 2.4.0.1.** A function f is  $C^k$  smooth iff  $f', f'', \ldots, f^{(k-1)}$  are continuous.

**Proposition 2.4.1.** For a  $C^1$  smooth function  $f \in C^1$  with Fourier coefficients  $c_n$  and derivative f' with Fourier coefficients  $c'_n$ .

$$c'_n = inc_n$$

**Theorem 2.4.1.** For a  $C^k$  smooth function  $f \in C^k$  with Fourier coefficients  $c_n$  and derivatives  $f^{(\ell)}$  with Fourier coefficients  $c_n^{(\ell)}$ .

$$c_n^{(k)} = (in)^\ell c_n, \quad \forall n \in \{0, 1, \dots, k\}$$

**Proposition 2.4.2.** For a real valued function  $f: [a, b] \to \mathbb{R}, c_n = \frac{a_n}{2} - \frac{ib_n}{2}$ .

**Corollary 2.4.1.1.** For a  $C^k$  smooth function  $f \in C^k$ , there exists a sequence  $a_n \to 0$  as  $|n| \to \infty$  such that

$$|c_n| \le a_n |n|^{-k}, \quad \forall n \in \mathbb{Z} - \{0\}$$

**Theorem 2.4.2.** For a  $C^k$  smooth function  $f:[a,b] \to \mathbb{C} \in C^k$ , there exists a constant  $c \in \mathbb{R}^+$  such that

$$|f(\theta) - S_N^f(\theta)| \le \frac{c}{N}, \quad \forall \theta \in [a, b]$$

**Theorem 2.4.3.** Let  $g, f \in C^1$  be  $2\pi$ -periodic functions then

$$(f*g)(\theta) = \frac{1}{2\pi} \int_{-\pi}^{\pi} f(y)g(\theta - y)dy, \quad \widehat{(f*g)}_n = \widehat{f}_n \cdot \widehat{g}_n$$

#### 2.5 Aliasing Error

**Definition 2.5.1.** The aliased Fourier coefficients denoted  $\tilde{c}_n$  are defined

$$\tilde{c}_n := \frac{(-1)^n}{N} \sum_{k=0}^{N-1} f\left(-\pi + k \cdot \frac{2\pi}{N}\right) e^{\frac{-2\pi i n k}{N}}$$

**Theorem 2.5.1.** Aliased Fourier coefficients  $\tilde{c}_n$  with N samples can be written in terms of the exact Fourier coefficients  $c_n$ ,

$$\tilde{c}_n = c_n + \sum_{|g|>1} c_{n+gN}$$

## Chapter 3

## Hilbert Spaces

#### 3.1 Inner Product Spaces

**Definition 3.1.1.** A vector space is a set V with addition and scalar multiplication such that the following properties hold

- Commutativity:  $v + w = w + v \ \forall \ v, w \in V$
- Associativity:  $(u+v) + w = u + (w+v) \ \forall \ u, v, w \in V$
- Zero Vector:  $\exists$  a vector 0 such that for any vector  $v \in V$ , v + 0 = v
- Additive Inverse: for any vector  $v \in V$  there exists a vector  $-v \in V$  such that v v = 0
- Multiplicative Identity: for any vector  $v \in V, v \cdot 1 = v$
- Additive Conservation: for any two vectors  $v, w \in V, v + w \in V$
- Multiplicative Conservation: for any vector  $v \in V$  and any scalar a, we have  $av \in V$

**Definition 3.1.2.** An inner product denoted  $\langle \cdot, \cdot, \rangle : V^2 \to \mathbb{C}$  is a function taking two vectors in a vector space V to  $\mathbb{C}$  such that for all  $u, v, w \in V$  and  $\alpha \in \mathbb{C}$ ,

- $\langle u + v, w \rangle = \langle u, w \rangle + \langle v, w \rangle.$
- $\langle \alpha v, w \rangle = \alpha \langle v, w \rangle$
- $\langle v, w \rangle = \widehat{\langle w, v \rangle}$
- $\langle v, v \in \mathbb{R}^+$  and  $\langle v, v \rangle = 0 \iff v = 0$ .

**Definition 3.1.3.** An **inner product space** is a vector space equipped with an inner product.

**Definition 3.1.4.** The norm of a vector  $v \in V$  denoted ||v|| is defined

$$||v|| = \sqrt{\langle v, v \rangle}$$

**Proposition 3.1.1.** For an inner product space V, any vectors  $v, w \in V$ , and any scalar  $\alpha \in \mathbb{C}$ ,

- $||\alpha v|| = |\alpha|||v||$
- $||v|| = 0 \iff v = 0$
- $||v + w|| \le ||v|| + ||w||$

**Proposition 3.1.2.** The Cauchy Schwartz inequality state that for any two vectors  $v, w \in V$  in an inner product space,

 $|\langle v, w \rangle| \le ||v||||w||$ 

#### 3.2 Hilbert Spaces

**Definition 3.2.1.** An orthogonal set of vectors  $\{v_j\}_{j \in I} \subset V$  is a set of vectors in an inner product space such that

$$\langle v_j, v_\ell \rangle = \delta_{j,\ell}, \quad \forall j, \ell \in I$$

**Theorem 3.2.1. General Bessel's Inequality** states that for any vector  $f \in V$  and any orthonormal set of vectors  $\{v_j\}_{j \in I}$  in an inner product space,

$$\sum_{j \in I} |\langle f, v_j|^2 \le ||f||^2$$

**Definition 3.2.2.** A **Cauchy sequence** of vectors  $\{v_j\}_{j=1}^{\infty} \subset V$  is a sequence in an inner product space such that  $\forall \varepsilon > 0$  there exists  $N \in \mathbb{N}$  such that  $\forall n, m \ge N$ ,  $||v_n - v_m|| \le \varepsilon$ .

**Definition 3.2.3.** A **complete inner product space** is an inner product space where every Cauchy sequence has a limit point.

Definition 3.2.4. A Hilbert space is a complete inner product space.

**Definition 3.2.5.** A sequence  $v_j$  converges in a Hilbert space H iff there exists  $v \in H$  such that  $\lim_{j\to\infty} ||v_j - v|| = 0$ .

**Definition 3.2.6.** The limit of a convergent sequence  $v_j$  is defined as the vector  $v \in H$  such that  $\lim_{j\to\infty} ||v_j - v|| = 0$ .

Proposition 3.2.1. The limit of a sequence is unique.

**Definition 3.2.7.** An orthonormal set of vectors  $\{v_j\}_{j=1}^N$  is a **basis** iff

$$\sum_{j=1}^{\infty} \langle f, v_j \rangle v_j = f, \quad \forall f \in H$$

**Proposition 3.2.2.** For an orthonormal set of vectors  $\{v_j\}_{j=1}^N$  and any vector  $f \in H$ ,

$$\langle \sum_{j=1}^{\infty} \langle f, v_j \rangle v_j, v_\ell \rangle = \langle f, v_\ell \rangle$$

**Theorem 3.2.2.** Let  $\{v_j\}_{j=1}^N$  be an orthonormal set of vectors in a Hilbert space H, the following are equivalent

•  $\{v_j\}_{j=1}^N$  is an orthonormal basis of H.

• 
$$\forall f \in H, f = \sum_{j=1}^{\infty} \langle f, v_j \rangle v_j.$$

- $\langle f, v_j \rangle = 0$  for all j, if and only if f = 0.
- $\forall f \in H, ||f||^2 = \sum_{j=1}^{\infty} |\langle v_j, f \rangle|^2.$

#### **3.3** Sets of Functions

**Definition 3.3.1.** The set of  $C^k$  smooth functions denoted  $C^k(D)$  is the set of continuous functions  $f: D \to \mathbb{C}$  such that f has k continuous derivatives.

**Definition 3.3.2.** The set of  $C^{\infty}$  smooth functions denoted  $C^{\infty}(D)$  is the set of continuous functions  $f: D \to \mathbb{C}$  with infinitely many continuous derivatives.

**Definition 3.3.3.** The set of Lebesgue integrable functions denoted  $L^p(D)$  is the set of functions  $f: D \to \mathbb{C}$  such that

$$\int_D |f(x)|^p dx < \infty$$

**Theorem 3.3.1.**  $L^2([a,b]) = \{f: [a,b] \to \mathbb{C}: \int_a^b |f(x)|^2 dx < \infty\}$  is a Hilbert space with inner product

$$\langle f,g\rangle = \int_a^b f(x)\overline{g(x)}dx$$

**Theorem 3.3.2.**  $\forall f \in L^2([a,b]) \text{ and } \varepsilon > 0 \text{ there exists } \tilde{f} \in C^{\infty}([a,b]) \text{ such that } ||f - \tilde{f}|| < \varepsilon.$ **Theorem 3.3.3.**  $\{e^{inx}\}_{n \in \mathbb{Z}}$  is a basis in  $L^2([a,b])$ .

#### 3.4 Convergence

**Definition 3.4.1.** A sequence of functions  $\{f_n\}$  is **pointwise convergent** to a function  $f: D \to \mathbb{C}$  iff for all  $x \in D$ ,

$$\lim_{n \to \infty} f_n(x) = f(x)$$

**Definition 3.4.2.** A sequence of functions  $\{f_n\}$  is **uniform convergent** to a function  $f: D \to \mathbb{C}$  iff for any  $\epsilon > 0$ , there exists  $N \in \mathbb{N}$  such that for all  $x \in D$  and n > N,

$$|f_n(x) - f(x)| < \epsilon$$

#### 3.5 Continuous Convolution and Fourier Transform

**Definition 3.5.1.** The continuous convolution (f \* g) of two functions f and g is defined

$$(f*g)(x) = \int_{-\infty}^{\infty} f(x-y)g(y)dy$$

**Theorem 3.5.1.** For any  $f, g \in L^1 \cap L^2$ ,  $f * g \in L^1 \cap L^2$ .

**Definition 3.5.2.** The continuous Fourier transform  $\hat{f}$  of a function f is defined

$$\widehat{f}(\omega) = \int_{-\infty}^{\infty} f(x) e^{-i\omega x} dx$$

**Definition 3.5.3.**  $C_0 \subset L^2(\mathbb{R})$  is the subset of continuous in  $L^2(\mathbb{R})$ .

**Theorem 3.5.2.** Let  $f \in L^2(\mathbb{R})$  then  $\forall \varepsilon > 0$ , there exists  $\tilde{N} \in \mathbb{Z}^+$  and continuous  $\tilde{f} \in L^2([-\tilde{N}, \tilde{N}]) \subset L^2(\mathbb{R})$  such that  $||f - \tilde{f}|| \leq \varepsilon$ .

**Corollary 3.5.2.1.**  $C_0$  is dense in  $L^2(\mathbb{R})$ .

**Theorem 3.5.3.** Let  $f, g \in L^1 \cap L^2$  and suppose that g has k bounded continuous derivatives  $g', g'', \ldots, g^{(k)} \in L^1 \cap L^2$  then f \* g also has k-derivatives and

$$(f * g)^{(\ell)} = (f * g^{(k)})(x), \quad \forall \ell \in 0, 1, \dots, k$$

"You're apparently majoring in mathematics, and this is the most important topic in mathematics, so I win!"

- "When N is up to you, use a power of two!"
- "And therefore we can conclude that everything is peachy."
- "As long as its countable, like whatever who cares!"
- "Let's anthropomorphize the Fourier series."
- "You just have to be ready to go from zero to frickin' abstract!"
- "Are you Hilbert's Friend? Then why are you in his space."
- "I don't think any of you would do that, but you never know what your students are capable of."
- "But how does this theorem make you feel?"